



SystemC-based Co-Simulation for ESL HW/SW Co-Design of Heterogeneous Parallel Embedded Systems

Supervisor: Dott. Ric. Ing. Luigi Pomante

Co-Supervisor: Dott. Ric. Ing. Vittoriano Muttillio

Candidate: Marinella Negrini
265205



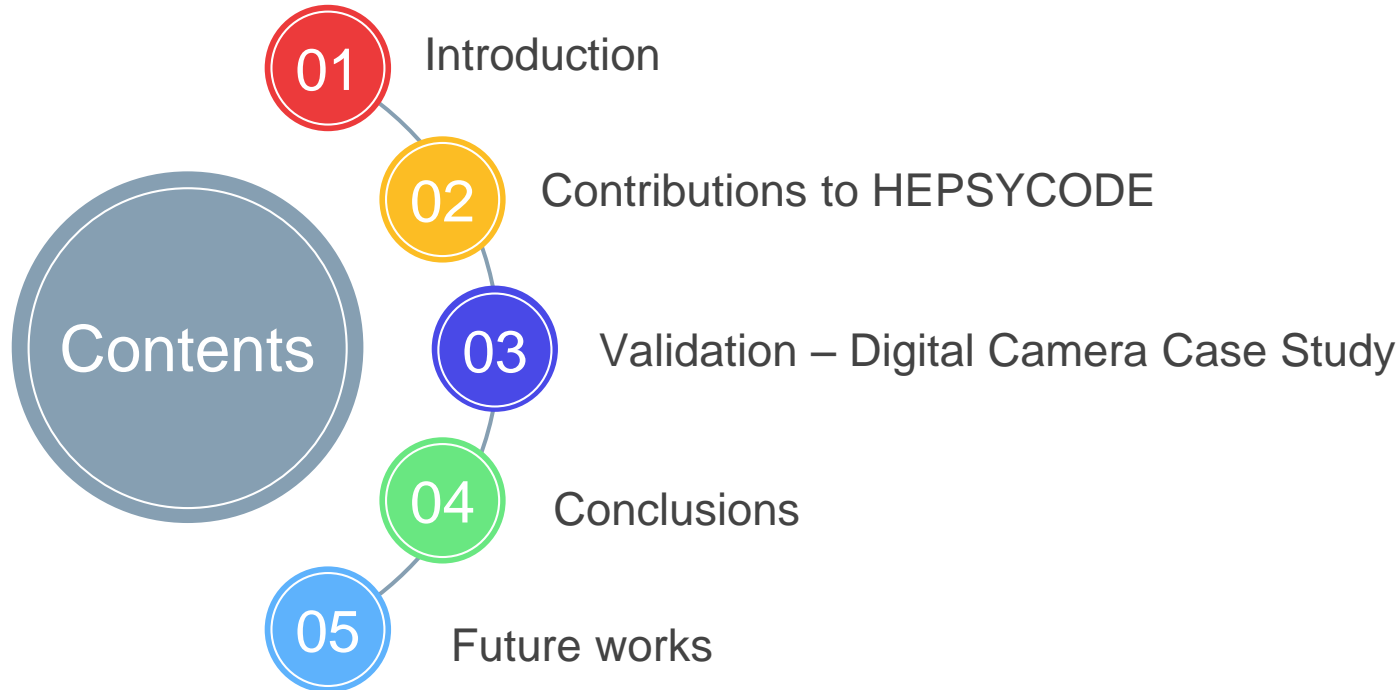
Main Purpose of this thesis

- Extend **HEPSIM** (part of *HEPSYCODE* methodology)
 - Multi-Link
 - Energy
 - Multiple CC4CS
 - CTF-compliant trace generation
- Validate the extension with a specific **Case Study**



www.hepsycode.com/

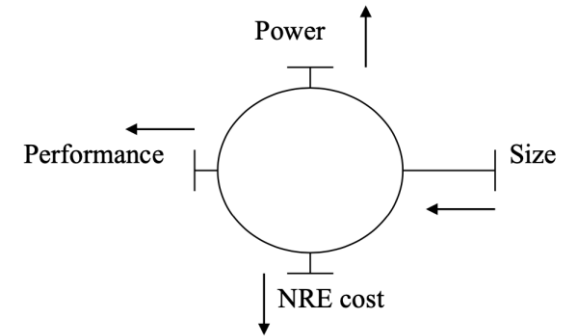
SystemC-based Co-Simulation for ESL HW/SW Co-Design of Heterogeneous Parallel Embedded Systems



01 Introduction: ESL HW/SW Co-Design

- ESL HW/SW Co-Design emphasizes a unified view of HW and SW at system level
- Embedded System Design is a complex task
- Heterogeneous technologies on a single chip (MP-SoC)
- Respect **Functional Requirements** and optimize competing

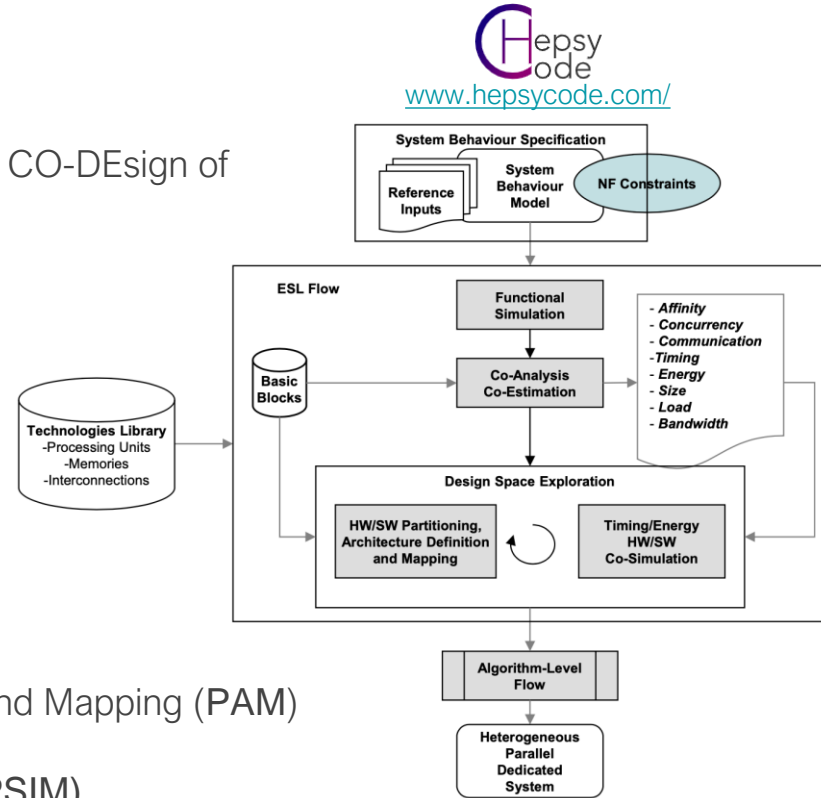
Design Metrics



01 Introduction: HEPSYCODE

- HEPSYCODE = System-Level methodology for HW/SW CO-DEsign of HEterogeneous Parallel dedicated SYstems
- System Behaviour Model
- Functional Simulation
- Co-Analysis and Co-Estimation
- Design Space Exploration

- HW/SW Partitioning, Architecture Definition and Mapping (PAM)
- Timing/Energy HW/SW Co-Simulation (HEPSIM)

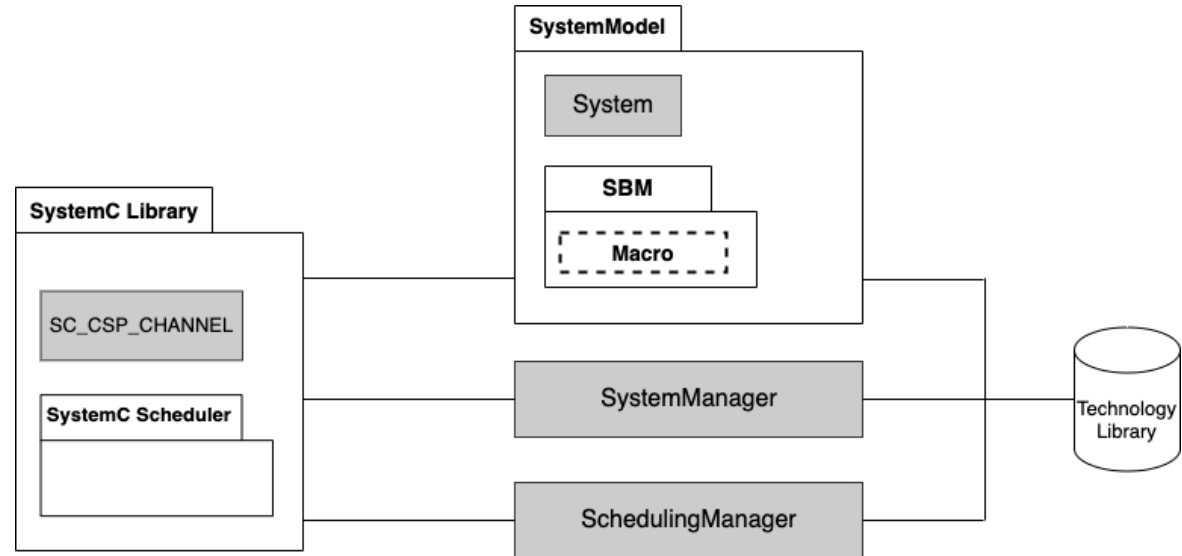


02

Contributions to HEPSCODE

HEPSIM Architecture

- SystemManager
- SchedulingManager
- Macros
- SC_CSP_CHANNEL
- Technology Library



02

Contributions to HEPSYCODE: HEPSIM Multi-Link

- Possibility of adopting multiple **Physical Links** in communications, instead of a single shared bus
- The available Links are inserted in Technologies Library
- Each Channel composing the SBM can be mapped on a different Physical Link

```
<mapping>
  <allocation CHid="0">
    <channelId CHid="0" Lname="RAM@20_min" value="1" />
  </allocation>
  <allocation CHid="1">
    <channelId CHid="1" Lname="RAM@20_min" value="1" />
  </allocation>
  <allocation CHid="2">
    <channelId CHid="2" Lname="RAM@20_min" value="1" />
  </allocation>
  <allocation CHid="3">
    <channelId CHid="3" Lname="RAM@20_min" value="1" />
  </allocation>
  <allocation CHid="4">
    <channelId CHid="4" Lname="GPIO_PORT@20_medium" value="7" />
  </allocation>
  <allocation CHid="5">
    <channelId CHid="5" Lname="GPIO_PIN_min" value="13" />
  </allocation>
</mapping>
```

02 Contributions to HEPSYCODE: Energy

- Program's statements (J4CS metric)

- Energy Per Instruction (EPI) method

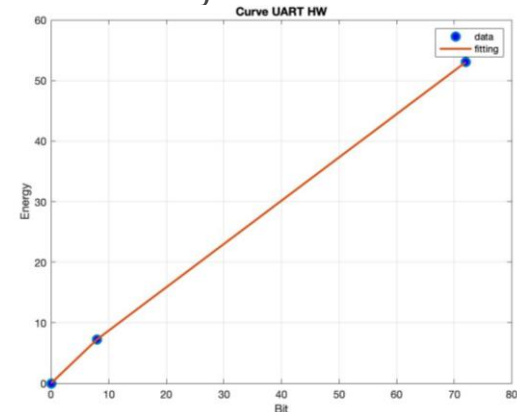
$$\text{SW: } J4CS = EPI \times I4CS = \frac{P}{MIPS} \times \frac{I}{CS}$$

$$\text{HW: } J4CS = P \times \frac{1}{f} \times CC4CS = (V_{dd} \times I_{dd}) \times CC4CS \times \frac{1}{f}$$

- Energy Per Cycle (EPC) method

$$J4CS = EPC \times CC4CS = \frac{P}{f} \times CC4CS$$

- Context Switch: $CS_{EN} = CS_{OH} \times P$
- Data transfers: characterization of Links in the TL with the coefficients of an interpolating polynomial of degree 2 (energy as a function of #bits transmitted)



02 Contributions to HEPSYCODE: Multiple CC4CS for different data types

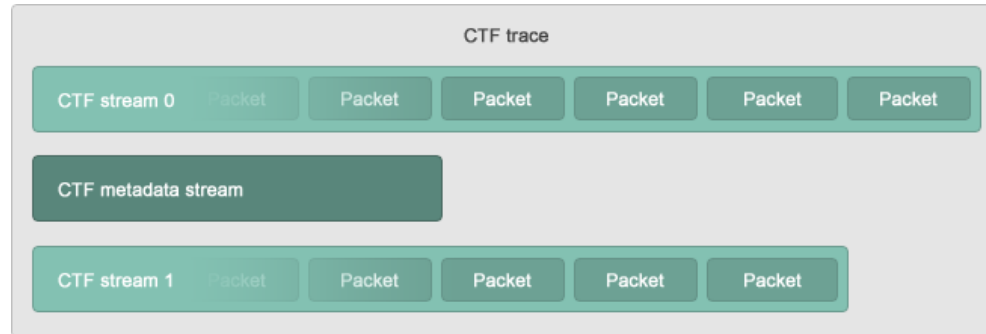
- **CC4CS metric:** number of clock cycles needed by a processor to execute a common C statement
- Possibility to distinguish between processes, according to their dominant data type
- Processors in the TL are characterized by a set of CC4CS metrics (one for each data type)
- Designers specify the dominant data type for each process of the SBM

```
<processingUnit>
  <name>MPU8051@12</name>
  <idprocessor>0</idprocessor>
  <processorType>GPP</processorType>
  <cost>1</cost>
  <ISA>8051</ISA>
  <frequency>12</frequency>
  <CC4SminInt8>84.9</CC4SminInt8>
  <CC4SmaxInt8>139.8</CC4SmaxInt8>
  <CC4SminInt16>118.4</CC4SminInt16>
  <CC4SmaxInt16>190.1</CC4SmaxInt16>
  <CC4SminInt32>166.3</CC4SminInt32>
  <CC4SmaxInt32>279.7</CC4SmaxInt32>
  <CC4SminFloat>293.5</CC4SminFloat>
  <CC4SmaxFloat>614.6</CC4SmaxFloat>
  <CC4Smin>125.5</CC4Smin>
  <CC4Smax>293.3</CC4Smax>
  <Power>0.6</Power>
  <MIPS>0.72</MIPS>
  <I4CSmin>7.5</I4CSmin>
  <I4CSmax>17.2</I4CSmax>
  <Vdd>6</Vdd>
  <Idd>NA</Idd>
  <overheadCS>405</overheadCS>
  <capacity />
</processingUnit>
```

02

Contributions to HEPSYCODE: HEPSIM CTF-compliant trace generation

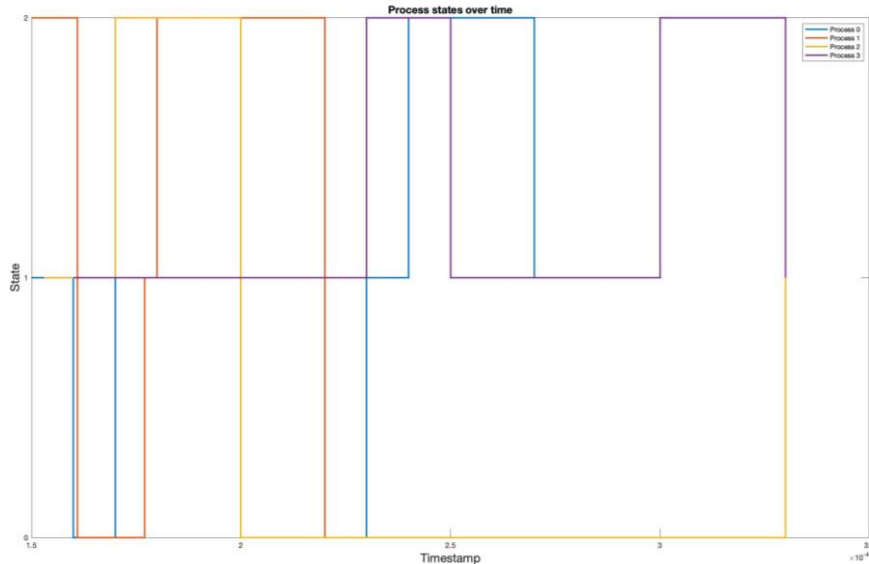
- The **Common Trace Format (CTF)** is a binary trace format
- The CTF is the reference format adopted in **FitOptiVis**
- CTF Trace = multiple **streams** of binary **events** (organized in **packets**) + **metadata** stream
- **Babeltrace** is the reference implementation of the CTF (Python3 bindings to read and write the CTF)



02

Contributions to HEPSYCODE: HEPSIM CTF-compliant trace generation

- HEPSIM generates a **LOG** during the execution
- A CTF trace is generated from the LOG file



```
0.0002265 - PS:2 - 0
0.0002265 - CH:4 - 2
0.0002265 - PS:2 - 0
0.0002265 - SC:1 - 2
0.0002271 - CH:4 - 1
0.0002271 - CH:4 - 0
```



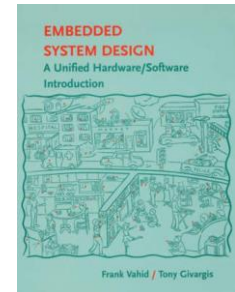
```
marinella@marinella-VirtualBox: /home/ctf$ ls -all
total 16024
drwxrwxrwx 2 root root 4096 ott 1 08:39 .
drwxr-xr-x 4 root root 4096 ott 1 08:39 ..
-rw-rw-r-- 1 marinella marinella 2083 ott 1 08:39 metadata
-rw-rw-r-- 1 marinella marinella 1376256 ott 1 08:39 stream_profiler_1_0
-rw-rw-r-- 1 marinella marinella 32768 ott 1 08:39 stream_profiler_1_1
-rw-rw-r-- 1 marinella marinella 917504 ott 1 08:39 stream_profiler_1_2
-rw-rw-r-- 1 marinella marinella 0 ott 1 08:39 stream_profiler_1_3
-rw-rw-r-- 1 marinella marinella 13369344 ott 1 08:39 stream_profiler_1_4
-rw-rw-r-- 1 marinella marinella 0 ott 1 08:39 stream_profiler_1_5
-rw-rw-r-- 1 marinella marinella 688128 ott 1 08:39 stream_profiler_1_6
```



03

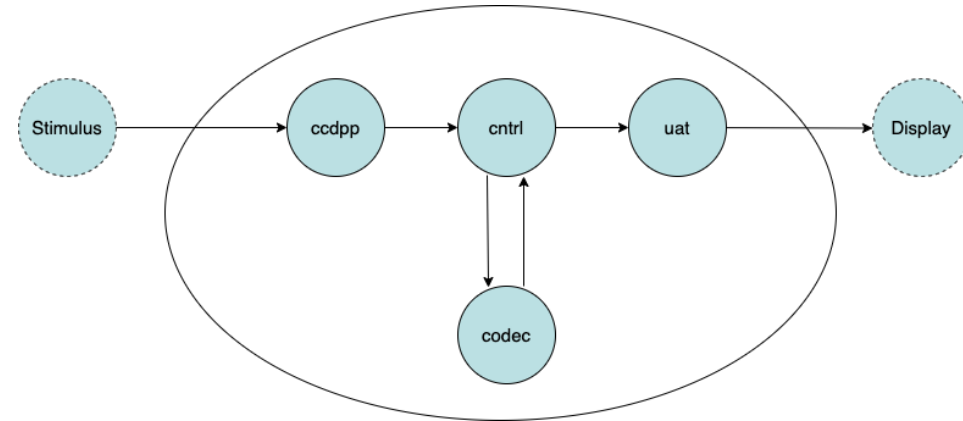
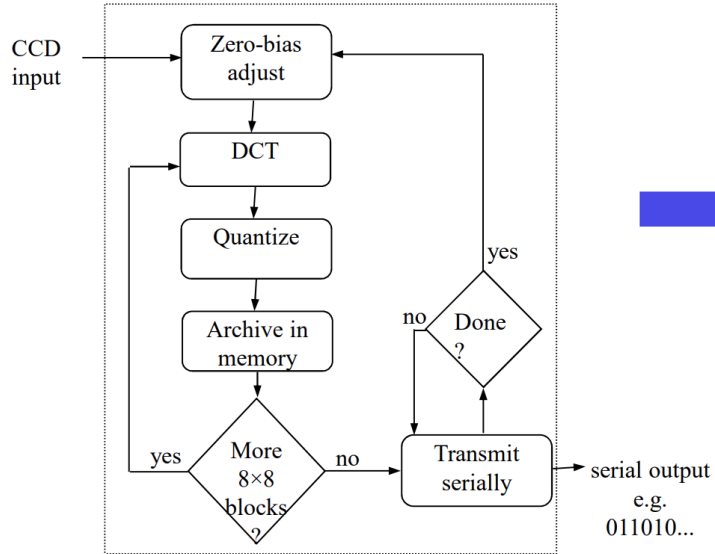
Validation – DC Case Study: objectives

- Case study presented in the book «*Embedded System Design: A Unified Hardware/Software Introduction*», by T.Givargis and F.Vahid
- Digital Camera performing a simplified **JPEG compression** and successively improved **implementations**
- **Validation** of the extensions, **comparison** of the results and **DSE**



03

Validation – DC Case Study: Functional Specification



03 Validation – DC Case Study: Implementations

Four different implementations:

1. Microcontroller (8051) alone (AllSW)
2. Microcontroller (8051) and HW CCDPP/UART
3. Microcontroller (8051) and Fixed-Point CODEC and HW CCDPP/UART
4. Microcontroller (8051) and HW CCDPP/UART and HW Fixed-Point CODEC

		Imp1 (manually estimated ccdpp only)	Imp2	Imp3	Imp4
VHDL (RTL) simulation	Performance (second)	near 0.5	9.1	1.5	0.099
	Power (Watt)	-	0.033	0.033	0.040
ASIC synthesis tool (gate-level)	Size (gate)	-	98000	90000	128000
	Energy (Joule)	-	0.30	0.050	0.0040

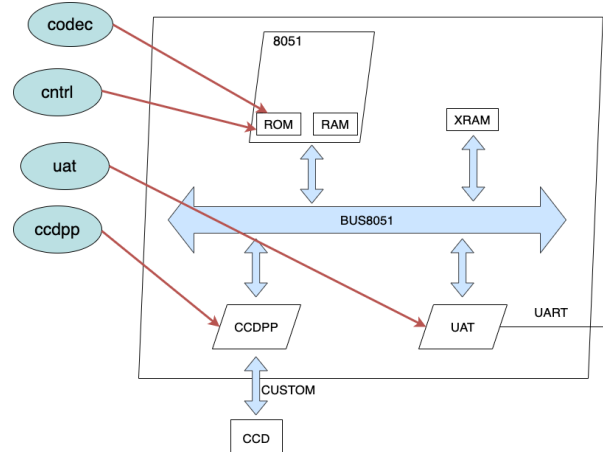
03

Validation – DC Case Study: Simulation with HEPSIM Processors in the TL

Processor	Frequency	CC4CSmin	CC4CSmax	Power	Vdd	Idd	I4CSmin	I4CSmax	MIPS	CS_OH
Intel 8051 (GPP)	12MHz	125.5	293.3	600mW	6V	-	7.5	17.2	0.72	405us
	20MHz								1.2	243us
Xilinx Artix7 (FPGA)	12MHz	0.9	1.9	-	2V	15uA	-	-	-	-
	20MHz								-	-

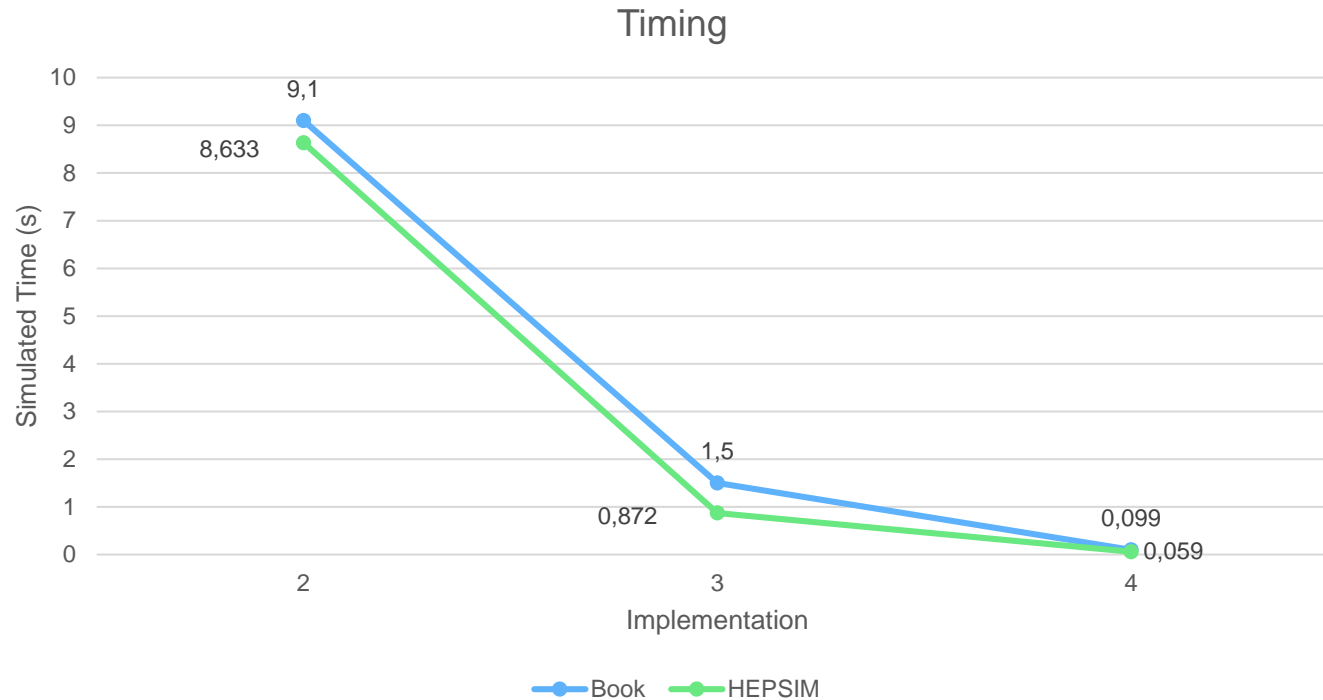
Manual mapping to reproduce the Implementations

Example: Implementation 2 →



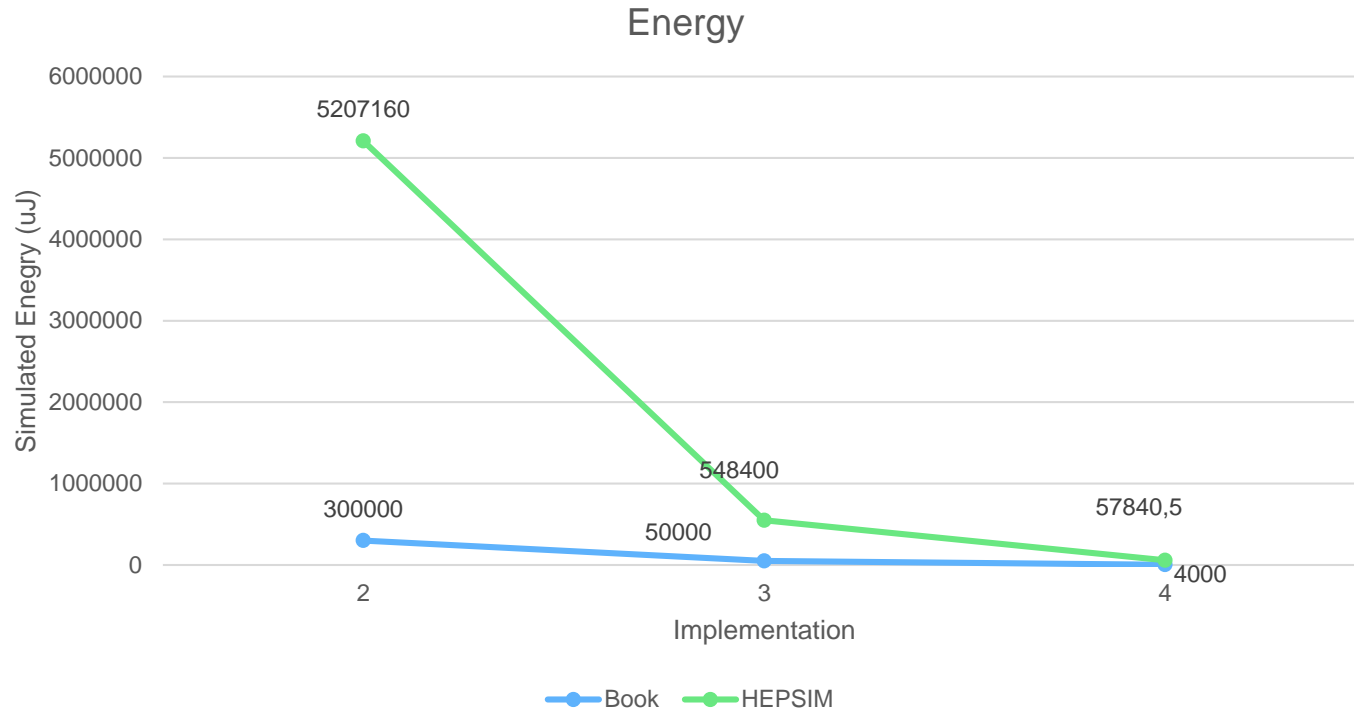
03

Validation – DC Case Study: Results (updated)



03

Validation – DC Case Study: Results (updated)



03

Validation – DC Case Study: Analysis and Considerations (updated)

Average Relative Errors (16x16)

Av. Rel. Error Time	Av. Rel. Error Energy
29,1%	N/A (SoC vs SoB)

HEPSIM vs RTL simulation

		HEPSIM	RTL
Simulation Time	Implementation 2	~10 seconds	~15 minutes
	Implementation 3	~10 seconds	~10 minutes
	Implementation 4	~5 seconds	~5 minutes
Modeling Time		Some minutes	Some hours

- HEPSIM estimation results are less **accurate** than results obtained via RTL simulation (System-level vs RTL)
- However, the HEPSIM estimation results are **reliable** (comparison and estimation)
- HEPSIM **Simulation** requires less time than RTL Simulation
- HEPSIM **Modeling** requires less time than RTL modeling

04

Conclusions

- HW/SW Co-Design techniques and HEPSYCODE
- Extend HEPSIM
- Validate using a Case Study
- Development of the SBM for parallel DC
- Deliverable D3.3 FitOptiVis

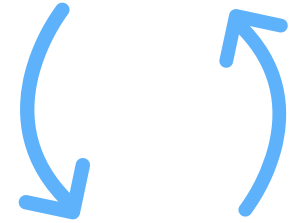


smart IntegraTion and OPTimisation Technologies for
highly efficient Image and Video processing Systems
<https://cordis.europa.eu/project/id/783162>

05

Future works

- Model SW partitions based on **hypervisor**
- Consider **Power** analysis and peak power
- Model with **Multi-MoC**



Thank you for your attention!